

最小作用量原理: $\delta S = 0$ 给出运动方程.

$$\begin{aligned} \delta S &= \int dt \left\{ \delta x(t) \cdot \frac{\partial L}{\partial x} + \delta \dot{x} \cdot \frac{\partial L}{\partial \dot{x}} + \delta p \cdot \frac{\partial L}{\partial p} \right\} \\ &= \int dt \left\{ \delta x(t) \cdot \underbrace{\left[\frac{\partial L}{\partial x} - \frac{d}{dt} \frac{\partial L}{\partial \dot{x}} \right]}_{\delta S / \delta x} + \delta p \cdot \underbrace{\frac{\partial L}{\partial p}}_{\delta S / \delta p} \right\} \end{aligned}$$

运动方程由任意变化 δx , δp , 有 $\delta S = 0$. 给出:

$$\textcircled{1} \quad \frac{\partial L}{\partial x} = \frac{d}{dt} \frac{\partial L}{\partial \dot{x}} \Rightarrow \frac{dp}{dt} = -\frac{\partial H}{\partial x}$$

$$\textcircled{2} \quad \frac{\partial L}{\partial p} = 0 \Rightarrow \frac{dx}{dt} = \frac{\partial H}{\partial p}$$

或者. $H(x, p) = \frac{p \cdot \dot{x}}{2} + V(x) \Rightarrow L = +\frac{p \cdot \dot{x}}{2} - V(x)$

① 经典哈密顿方程.

回到量子力学:

$$S = \int_t^{t'} dt [p(t) \dot{x}(t) - H(p(t), x(t))]$$

与经典力学一致.

但是每一条路径 (path) 有一个“振幅” $= e^{\frac{i}{\hbar} S}$

$x(t)$, $p(t)$ 任意, 独立, 不保证 $p(t) = m \dot{x}(t)$.

由于 S 中对 $p(t)$ 的依赖 取决于

$$\int_t^{t'} \left[p(t) \dot{x}(t) - \frac{p(t)^2}{2m} \right] dt = \int_t^{t'} \left(-\frac{1}{2m} (p(t) - m \dot{x}(t))^2 + \frac{m \dot{x}(t)^2}{2} \right) dt$$

所以对 $U(x', t'; x, t)$ 中的 $\mathcal{D}p$ 积分. (高斯积分)

$$\int_{\mathcal{C}} \mathcal{D}p(t) = \int_{\mathcal{C}} \mathcal{D}p(t) = \mathcal{N} \sqrt{\frac{m}{2\pi i \hbar t}}$$

$$(公式 B) U(x', t'; x, t) = \int_{x(t)=x}^{x(t')=x'} \mathcal{D}x(t) e^{\frac{i}{\hbar} S}$$

$$S = \int_t^{t'} dt \left(\frac{m \dot{x}(t)^2}{2} - V(x(t)) \right)$$

公式 A 与 B 都对, 但 A 更基本. 因为 $i\hbar \dot{x}$ 可解释为 Berry phase
 也有情况无法积分 $P(t)$ (以后讲)

$\delta S = 0 \Rightarrow$ 经典方程. 最小作用量

• 量子: 每条路径都有贡献. 但是如果有“干涉”, S 差一点
 phase $\frac{iS}{\hbar}$ 差很大! 平均起来为 0. 除了 $\delta S = 0$ 的路径.

• 无算符. 代价: 无穷维积分.

• 推导 $[\hat{x}, \hat{p}] = i\hbar$.

设一个物理量 $F(x, p)$. 计算它的“路径平均”

$$\langle F(\{x\}, \{p\}) \rangle \equiv \int \mathcal{D}x(t) \mathcal{D}p(t) F(\{x\}, \{p\}) e^{\frac{i}{\hbar} S(\{x\}, \{p\})}$$

改写 $F(\{x\}, \{p\}) \rightarrow F(x_1, \dots, x_{N+1}; p_0, p_1, \dots, p_{N+1}) \equiv F(x_k, p_k)$

$$\int \mathcal{D}x \mathcal{D}p \rightarrow \prod_k \int dx_k dp_k$$

变换: $x_k = \tilde{x}_k + y_k, \quad p_k = \tilde{p}_k + \zeta_k, \quad y_k, \zeta_k$ 无穷小

$$\langle F(x_k, p_k) \rangle = \int \prod_k d\tilde{x}_k d\tilde{p}_k F(\tilde{x}_k + y_k, \tilde{p}_k + \zeta_k) \times e^{\frac{i}{\hbar} S(\tilde{x}_k + y_k, \tilde{p}_k + \zeta_k)}$$

$$= \int \prod_k d\tilde{x}_k d\tilde{p}_k \left(F + \sum_k y_k \frac{\partial F}{\partial x_k} + \sum_k \zeta_k \frac{\partial F}{\partial p_k} \right)$$

$$\times \left(1 + \frac{i}{\hbar} \sum_k y_k \frac{\partial S}{\partial x_k} + \frac{i}{\hbar} \sum_k \zeta_k \frac{\partial S}{\partial p_k} \right) e^{iS/\hbar}$$

$$= \langle F(x_k, p_k) \rangle + \sum_k y_k \left\langle \frac{\partial F}{\partial x_k} + \frac{i}{\hbar} F \frac{\partial S}{\partial x_k} \right\rangle$$

$$+ \sum_k \zeta_k \left\langle \frac{\partial F}{\partial p_k} + \frac{i}{\hbar} F \frac{\partial S}{\partial p_k} \right\rangle$$

由于 q_k 与 p_k 任意

$$\left\langle \frac{\partial F}{\partial x_k} \right\rangle = -\frac{i}{\hbar} \left\langle F \frac{\partial S}{\partial x_k} \right\rangle \quad (1)$$

$$\left\langle \frac{\partial F}{\partial p_k} \right\rangle = -\frac{i}{\hbar} \left\langle F \frac{\partial S}{\partial p_k} \right\rangle \quad (2)$$

如果: $F(x_k, p_k)$ 是 $P(k_0)$ (又取在 k_0 处 P)

$$\text{由(2)} \quad 1 = -\frac{i}{\hbar} \left\langle P(k_0) \frac{\partial S}{\partial p_{k_0}} \right\rangle$$

$$\text{由于 } S = \sum_k P_k (x_{k+1} - x_k) - \Delta t \sum_k H(P_k, x_k)$$

$$\text{有: } \frac{\partial S}{\partial p_{k_0}} = x_{k_0+1} - x_{k_0} - \Delta t \frac{\partial H}{\partial p_{k_0}}$$

当 $\Delta t \rightarrow 0$,

$$\boxed{i\hbar = \langle P(k_0) (x_{k_0+1} - x_{k_0}) \rangle} \quad (C)$$

前面推导

$$\langle x \rangle_{t=t_0} = \langle x_{k_0+1} P_{k_0} \rangle$$

$$\langle p \rangle_{t=t_0} = \langle P_{k_0} x_{k_0} \rangle$$

$$\langle x_{k_0+1} | x | P_{k_0} \rangle \langle P_{k_0} | P | x_{k_0} \rangle$$

$$\langle x' | P | x \rangle = \langle x' | P | P \rangle \langle P | x | x \rangle$$

因此 (C) 在等时对应: $[\hat{x}, \hat{p}] = i\hbar$