

第十六讲

我们先来回顾一下 RG 变换.

$$\text{给定 } F[\phi] = \int d^d x \left[\frac{1}{2} \nabla \phi \cdot \nabla \phi + \frac{1}{2} r_0 \phi^2 + g \phi^4 + \dots \right] \rightarrow \text{参数空间 } \vec{\mu} = (r_0, g, \dots)$$

1. 粗粒化: $F[\phi]$ 写到动量空间 $F[\phi_k]$

$$\phi_k = \phi_k^- + \phi_k^+, \quad \phi_k^- \text{ 在 } 0 < k < \frac{\Lambda}{3}, \quad \phi_k^+ \text{ 在 } \frac{\Lambda}{3} \leq k < \Lambda.$$

$$F[\phi_k] = F_0[\phi_k^-] + F_0[\phi_k^+] + F_I[\phi_k^-, \phi_k^+]$$

$$Z = \int \mathcal{D}\phi_k e^{-F[\phi_k]} = \int_{0 < k < \Lambda/3} \mathcal{D}\phi_k^- e^{-F_0[\phi_k^-]} \int_{\Lambda/3 \leq k < \Lambda} \mathcal{D}\phi_k^+ e^{-F_0[\phi_k^+] - F_I[\phi_k^-, \phi_k^+]} = \int_{0 < k < \Lambda/3} \mathcal{D}\phi_k^- e^{-F'[\phi_k^-]}$$

$$\text{对于 } F_G = \int d^d x \frac{1}{2} (\nabla \phi \cdot \nabla \phi + r_0 \phi^2) = \int_0^{\Lambda} \frac{d^d k}{(2\pi)^d} \frac{1}{2} (k^2 + r_0) |\phi_k|^2, \quad \vec{\mu} = r_0 \hat{e}_t$$

$$F'[\phi_k^-] = \int_0^{\Lambda/3} \frac{d^d k}{(2\pi)^d} \frac{1}{2} (k^2 + r_0') |\phi_k^-|^2 = \int d^d x \left[\frac{1}{2} \nabla \phi^- \cdot \nabla \phi^- + \frac{r_0'}{2} (\phi^-)^2 \right], \quad r_0' = r_0$$

一般情况: $F'[\phi^-] = \int d^d x \left[\frac{1}{2} \nabla \phi^- \cdot \nabla \phi^- + \frac{1}{2} r_0' (\phi^-)^2 + g' (\phi^-)^4 + \dots \right]$

2. rescale:

$$k' = \zeta k, \quad x' = \frac{x}{\zeta}, \quad \phi_{k'} = \zeta^{\Delta\phi_k} \phi_k, \quad \phi'(x) = \zeta^{\Delta\phi} \phi(x), \quad \Delta\phi_k = \Delta\phi - d$$

$$F[\phi] \rightarrow F_\zeta[\phi'] = \int d^d x \left[\frac{1}{2} \nabla_{x'} \phi'(x') \cdot \nabla_{x'} \phi'(x') + \frac{1}{2} r_0(\zeta) \phi'(x') \phi'(x') + g(\zeta) (\phi'(x'))^4 + \dots \right]$$

这就定义了: $\vec{\mu} \rightarrow \vec{\mu}(\zeta) = R_\zeta \vec{\mu}$

对于 F_G , $\vec{\mu}(\zeta) = r_0(\zeta) \hat{e}_t = \zeta^2 r_0 \hat{e}_t$

3. 不动点与附近的分析:

平凡不动点: $\vec{\mu}^*$ 对应 $\zeta = \infty$. 在 $\vec{\mu}^*$ 附近线性化 R_ζ

$$\vec{\mu} = \vec{\mu}^* + \delta\vec{\mu}, \quad \text{线性化: } \delta\vec{\mu}' = R_\zeta^L \delta\vec{\mu}$$

$$\delta\vec{\mu} = \sum_j t_j \vec{e}_j, \quad \delta\vec{\mu}' = \sum_j t_j \zeta^{\gamma_j} \vec{e}_j, \quad \frac{1}{\zeta} = \gamma_1$$

对于 F_G , $t_1 \rightarrow r_0, \quad \gamma_1 = 2. \Rightarrow \frac{1}{\zeta} = \frac{1}{2}$.

此外: 自洽要求: $\Delta\phi_k = -1 - \frac{d}{2} \Rightarrow \Delta\phi = \frac{d-2}{2} \Rightarrow \gamma = 0$.

现在考虑含 ϕ^4 项 in LG:

$$F[\phi] = \int d^d x \left[\underbrace{\frac{1}{2} \nabla \phi \cdot \nabla \phi + \frac{1}{2} r_0 \phi^2}_{F_G} + \underbrace{g_0 \phi^4}_{F_I} \right] = \int_0^{1/\Lambda} \frac{d^d k}{(2\pi)^d} \left[\frac{1}{2} (k^2 + r_0) \phi_k^2 + g_0 \phi_{k_1} \phi_{k_2} \phi_{k_3} \phi_{k_4} (2\pi)^d \delta(\vec{k}_1 + \vec{k}_2 + \vec{k}_3 + \vec{k}_4) \right]$$

用引 $\int d^d x e^{i k \cdot x} = (2\pi)^d \delta^d(k)$

(1). 粗粒化: $\phi_k = \phi_k^- + \phi_k^+$

$$F[\phi] = F_0[\phi^-] + F_0[\phi^+] + F_I[\phi^-, \phi^+] \leftarrow \text{选取 } F_G \text{ 为 } F_0$$

$$\text{其中 } F_0 = \int \frac{d^d k}{(2\pi)^d} \frac{1}{2} (k^2 + r_0) \phi_k \phi_k = \int_0^{1/\Lambda} \frac{d^d k}{(2\pi)^d} \frac{1}{2} (k^2 + r_0) \phi_k^- \phi_k^- + \int_{1/\Lambda}^{\Lambda} \frac{d^d k}{(2\pi)^d} \frac{1}{2} (k^2 + r_0) \phi_k^+ \phi_k^+$$

$$F_I = \int d^d x g_0 \phi^4 = \int \frac{d^d k}{(2\pi)^d} g_0 \phi_{k_1} \phi_{k_2} \phi_{k_3} \phi_{k_4} (2\pi)^d \delta(\vec{k}_1 + \vec{k}_2 + \vec{k}_3 + \vec{k}_4)$$

$$Z = \int \prod_{k < \Lambda} d\phi_k e^{-F} = \int \prod_{k < \Lambda/3} d\phi_k^- \left[e^{-F_0[\phi^-]} \cdot \int_{\Lambda/3 < k < \Lambda} \prod d\phi_k^+ e^{-F_0[\phi^+] - F_I[\phi^-, \phi^+]} \right] = \int \prod_{k < \Lambda/3} d\phi_k^- e^{-F'[\phi^-]}$$

$$\begin{aligned} e^{-F'[\phi^-]} &= e^{-F_0[\phi^-]} \cdot \int_{\Lambda/3 < k < \Lambda} \prod d\phi_k^+ e^{-F_0[\phi^+] - F_I[\phi^-, \phi^+]} \\ &= e^{-F_0[\phi^-]} \cdot \frac{\int \prod d\phi_k^+ e^{-F_0[\phi_k^+]} \cdot e^{-F_I[\phi_k^-, \phi_k^+]}}{\int \prod d\phi_k^+ e^{-F_0[\phi_k^+]}} \cdot \int \prod d\phi_k^+ e^{-F_0[\phi_k^+]} \\ &= e^{-F_0[\phi^-]} \langle e^{-F_I[\phi_k^-, \phi_k^+]} \rangle_+ e^{-A} \end{aligned}$$

定义了: $e^{-A} = \int \prod d\phi_k^+ e^{-F_0[\phi_k^+]} \rightarrow$ 高斯分布给出归一化因子

于是:

$$F'[\phi^-] = F_0[\phi_k^-] - \ln \langle e^{-F_I[\phi_k^-, \phi_k^+]} \rangle_+ - A$$

求助于微扰来计算 $\langle e^{-F_I} \rangle_+$

无量纲化: 设 $L_0 \equiv r_0^{-1/2}$, $\varphi \equiv \frac{\phi}{L_0^{1-d/2}}$, $\vec{r} \equiv \frac{\vec{x}}{L_0}$, $\bar{g}_0 \equiv \frac{g_0}{L_0^{d-4}}$

$$F_G = \int d^d r \left[L_0 (\nabla \varphi)^2 + \frac{1}{2} \varphi^2 \right], \quad F_I = \int d^d r \bar{g}_0 \varphi^4$$

当 $\bar{g} = g_0 r_0^{d/2} \ll 1$, 可以微扰展开 e^{-F_I} .

$$\ln \langle e^{-F_I} \rangle_+ = \ln \langle 1 - F_I + \frac{1}{2} F_I^2 + \dots \rangle_+ = \ln \left(1 - \langle F_I \rangle_+ + \frac{1}{2} \langle F_I^2 \rangle_+ + \dots \right)$$

再利用 $\ln(1+x) = x - \frac{1}{2} x^2 + \frac{1}{3} x^3 - \frac{1}{4} x^4 + \dots$, 设 $x = -\langle F_I \rangle_+ + \frac{1}{2} \langle F_I^2 \rangle_+ - \dots$

$$\Rightarrow \ln \langle e^{-F_I} \rangle_+ = -\langle F_I \rangle_+ + \frac{1}{2} [\langle F_I^2 \rangle_+ - \langle F_I \rangle_+^2] + \dots$$

也写作: $\langle e^{-F_I} \rangle_+ = e^{-\langle F_I \rangle_+ + \frac{1}{2} [\langle F_I^2 \rangle_+ - \langle F_I \rangle_+^2] + \dots}$

称累积展开.

• $\langle F_I \rangle$ 是微扰的一阶项 (g_0 一阶).

观察: $F_I[\phi_k^-, \phi_k^+] = g_0 \int_{i=1}^4 \frac{d^d k_i}{(2\pi)^d} \phi_{k_1} \phi_{k_2} \phi_{k_3} \phi_{k_4} (2\pi)^d \delta^d(\sum_i \vec{k}_i)$

每个 $\phi_k = \phi_k^- + \phi_k^+$, $\phi_{k_1} \phi_{k_2} \phi_{k_3} \phi_{k_4}$ 共 16 项, 可以分为 5 类

i) $\phi_{k_1}^- \phi_{k_2}^- \phi_{k_3}^- \phi_{k_4}^-$, 记作 $\langle F_I \rangle_4^{----}$ 不含任何 ϕ_k^+ , 贡献 $g_0 \int d^d \phi (\phi^-)^4$ 给 $F[\phi]$

ii) 4 $\phi_{k_1}^- \phi_{k_2}^- \phi_{k_3}^- \phi_{k_4}^+$, 一个 ϕ_k^+ 其 $\frac{1}{3} < k < 1$,

$$\langle F_I \rangle_4^{---+} = g_0 \int \prod_{i=1}^4 \frac{d^d k_i}{(2\pi)^d} \phi_{k_1}^- \phi_{k_2}^- \phi_{k_3}^- \langle \phi_{k_4}^+ \rangle_+ (2\pi)^d \delta^d(\sum_i \vec{k}_i)$$

$\langle \phi_{k_4}^+ \rangle_+ = \frac{1}{N} \int_0^\infty d\phi_{k_4}^+ \phi_{k_4}^+ e^{-\frac{g}{2} |\phi_{k_4}^+|^2} = 0$ 在 Gaussian 积分后消失

iii) 6 $\phi_{k_1}^- \phi_{k_2}^- \phi_{k_3}^+ \phi_{k_4}^+$: **重要**. $6 = C_4^2$. k_3 与 k_4 在 $1/3$ 与 1 之间, $\langle F_I \rangle_4^{--++}$, **需计算** $\langle \phi_{k_3}^+ \phi_{k_4}^+ \rangle_+$

iv) 4 $\phi_{k_1}^- \phi_{k_2}^+ \phi_{k_3}^+ \phi_{k_4}^+$, cubic in ϕ_k^+ , 消失 $\because \langle \phi_{k_2}^+ \phi_{k_3}^+ \phi_{k_4}^+ \rangle_+ = 0$

v) $\phi_{k_1}^+ \phi_{k_2}^+ \phi_{k_3}^+ \phi_{k_4}^+$, 不含 ϕ_k^- , 给出 free energy 中常数. **不重要**

• 计算: $\langle F_I \rangle_4^{--++} = 6 g_0 \int \prod_{i=1}^4 \frac{d^d k_i}{(2\pi)^d} \phi_{k_1}^- \phi_{k_2}^- \langle \phi_{k_3}^+ \phi_{k_4}^+ \rangle_+ (2\pi)^d \delta^d(\sum_i \vec{k}_i)$

如果 k_3 与 k_4 独立: $\langle \phi_{k_3}^+ \phi_{k_4}^+ \rangle_+ = 0$, $\because \langle \phi_{k_3}^+ \phi_{k_4}^+ \rangle_+ = \langle \phi_{k_3}^+ \rangle_+ \langle \phi_{k_4}^+ \rangle_+ = 0$. 两个独立高斯积分.

当 $\vec{k}_3 = -\vec{k}_4$ 即 $\phi_{k_3}^+ = (\phi_{k_4}^+)^+$, 积分才不为零

$$\langle \phi_{\vec{q}}^+ \phi_{-\vec{q}}^+ \rangle_+ = \frac{\int d\phi_{\vec{q}} d\phi_{-\vec{q}} |\phi_{\vec{q}}^+|^2 e^{-\frac{1}{2}(r_0 + q^2)|\phi_{\vec{q}}^+|^2}}{\int d\phi_{\vec{q}} d\phi_{-\vec{q}} e^{-\frac{1}{2}(r_0 + q^2)|\phi_{\vec{q}}^+|^2}} = \frac{1}{r_0 + q^2}$$

用独立高斯积分: $\frac{\int_{-\infty}^{\infty} dx x^2 e^{-\frac{a}{2}x^2}}{\int_{-\infty}^{\infty} dx e^{-\frac{a}{2}x^2}} = \frac{1}{a}$

也可由高斯路径积分公式: $\langle \phi(x) \phi(y) \rangle = G(x-y)$, $G(x-y) = \int \frac{d^d k}{(2\pi)^d} \frac{e^{-i\vec{k} \cdot (x-y)}}{r_0 + k^2}$ 得到.

所以 \vec{k} 连接形式: $\langle \phi_{k_3}^+ \phi_{k_4}^+ \rangle_+ = (2\pi)^d \delta^d(\vec{k}_3 + \vec{k}_4) G_0(\vec{k}_3)$, $G_0(\vec{k}_1) = \frac{1}{r_0 + k_1^2}$

最终: $\langle F_I \rangle_4^{--++} = 6 g_0 \int \prod_{i=1}^4 \frac{d^d k_i}{(2\pi)^d} \phi_{k_1}^- \phi_{k_2}^- G_0(\vec{k}_3) (2\pi)^d \delta^d(\vec{k}_3 + \vec{k}_4) (2\pi)^d \delta^d(\vec{k}_1 + \vec{k}_2 + \vec{k}_3 + \vec{k}_4)$

$$= 6 g_0 \int_{0}^{1/3} \frac{d^d k}{(2\pi)^d} \phi_{\vec{k}}^- \phi_{-\vec{k}}^- \int_{1/3}^1 \frac{d^d q}{(2\pi)^d} \frac{1}{r_0 + q^2} \quad (3)$$

$$\langle F_I \rangle_+^{-++} \text{ 与 } F_0[\phi^-] = \int_0^{1/\zeta} \frac{d^d k}{(2\pi)^d} \frac{1}{2} (r_0 + k^2) \phi_{\vec{k}}^- \phi_{-\vec{k}}^- \quad \text{合并.}$$

$$\Rightarrow \boxed{r_0' = r_0 + 12g_0 \int_{1/\zeta}^1 \frac{d^d q}{(2\pi)^d} \frac{1}{r_0 + q^2}}$$

RG 第二步: rescale: $\vec{k} \rightarrow \vec{k}' = \zeta \vec{k}, \quad \phi_{\vec{k}}^- \rightarrow \phi_{\vec{k}'}^- = \zeta^{\Delta\phi_k} \phi_{\vec{k}}^-$

$$\begin{aligned} F'[\phi] &= \int_0^{1/\zeta} \frac{d^d k}{(2\pi)^d} \frac{1}{2} (r_0' + k^2) \phi_{\vec{k}}^- \phi_{-\vec{k}}^- \\ &= \int_0^1 \frac{d^d k'}{(2\pi)^d} \zeta^{-d} \frac{1}{2} (r_0' + \zeta^{-2} k'^2) \zeta^{-2\Delta\phi_k} \phi_{\vec{k}'}^- \phi_{-\vec{k}'}^- \end{aligned}$$

• $k^2 \text{ 与 } \phi^2 \text{ 均 } \rightarrow 1 \rightarrow \zeta^{-2\Delta\phi_k - 2 - d} = \zeta^0 \Rightarrow \Delta\phi_k = -1 - \frac{d}{2}$

• $r_0(\zeta) = r_0' \zeta^{-2\Delta\phi_k - d} = \zeta^2 \left(r_0 + 12g_0 \int_{1/\zeta}^1 \frac{d^d q}{(2\pi)^d} \frac{1}{r_0 + q^2} \right) \quad (A)$

• $r_0 = 0$ 不再“不动”了. 因为有了来自 ϕ^4 的贡献.

• 再计算 $\langle F_I \rangle_+^{-++} = g_0 \int_0^{1/\zeta} \frac{d^d k_1}{(2\pi)^d} \frac{d^d k_2}{(2\pi)^d} \frac{d^d k_3}{(2\pi)^d} \frac{d^d k_4}{(2\pi)^d} \phi_{\vec{k}_1}^- \phi_{\vec{k}_2}^- \phi_{\vec{k}_3}^- \phi_{\vec{k}_4}^- (2\pi)^d \delta(\sum_i \vec{k}_i)$

构造 $F'[\phi]$ 中 ϕ^4 项

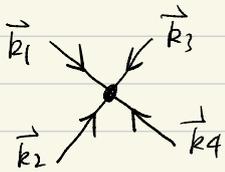
$$\begin{aligned} \text{rescale 之后} &= g_0 \int_0^1 \frac{\pi d^d k_i}{i (2\pi)^d} \zeta^{-4d - 4\Delta\phi_k} \phi_{\vec{k}_1}^- \phi_{\vec{k}_2}^- \phi_{\vec{k}_3}^- \phi_{\vec{k}_4}^- (2\pi)^d \delta(\sum_i \vec{k}_i) \\ &= g_0 \zeta^{-3d - 4(-1 - \frac{d}{2})} \int d^d x \phi^4(x) \quad (\delta(\zeta \vec{k}) = \zeta^{-d} \delta(\vec{k})) \end{aligned}$$

RP: $\boxed{g_0(\zeta) = g_0 \zeta^{4-d}} \quad (B)$

(A) 与 (B) 给出 $R_\zeta \vec{u} = \vec{u}(\zeta)$

Feynman Diagrams 来帮忙.

$$\langle F_I \rangle_+^{----} = g_0 \int_0^{1/\Lambda} \frac{d^d k_1}{(2\pi)^d} \frac{d^d k_2}{(2\pi)^d} \frac{d^d k_3}{(2\pi)^d} \frac{d^d k_4}{(2\pi)^d} \phi_{k_1}^- \phi_{k_2}^- \phi_{k_3}^- \phi_{k_4}^- (2\pi)^d \delta^d(\sum_i \vec{k}_i) = g_0 \int d^d x (\phi^-)^4$$

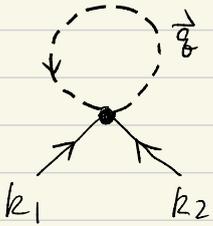


1. 外腿 (external leg): $\phi_{\vec{k}}$,

2. $\bullet = g_0 (2\pi)^d \delta(\vec{k}_1 + \vec{k}_2 + \vec{k}_3 + \vec{k}_4)$ 顶角 (vertex), 可理解为动量守恒

3. 对每一条 external leg 作积分 $\int_0^{1/\Lambda} \frac{d^d k}{(2\pi)^d}$

$$\langle F_I \rangle_+^{++--} = g_0 \int_0^{1/\Lambda} \frac{d^d k_1}{(2\pi)^d} \frac{d^d k_2}{(2\pi)^d} \phi_{k_1}^- \phi_{k_2}^- (2\pi)^d \delta^d(\vec{k}_1 + \vec{k}_2) \int_{1/\Lambda}^1 \frac{d^d q}{(2\pi)^d} \frac{1}{r_0 + q^2}$$



1. 两条腿 $\phi_{k_1}^+$ 和 $\phi_{k_2}^+$ 作平均后相连, 形成内线 (internal line)
内线携带动量 q 和因子 $G_0(q)$, 形成圈 (loop)

并积分 $\int_{1/\Lambda}^1 \frac{d^d q}{(2\pi)^d}$

2. 顶角 $\bullet = g_0 (2\pi)^d \delta(\vec{k}_1 + \vec{k}_2)$